

$$\begin{aligned}
& k_{10} \left(\zeta_{\mathbf{P1}}(t) - \zeta_1(t) \right) + \\
& 2 M_{\mathbf{P1}} \left(\cos(\theta(t)) R(t) + \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left(L_0 + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) + \eta_{\mathbf{P1}}(t) \right) \right) \\
& \zeta_{\mathbf{P1}}'(t) \left(\cos(\theta(t)) R'(t) - \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \\
& \quad \left(L_0 + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) + \eta_{\mathbf{P1}}(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) - \\
& \quad \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left(L_0 + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) + \eta_{\mathbf{P1}}(t) \right) \left(\theta'(t) + \psi'(t) \right) + \\
& \quad \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left(\eta_1'(t) + \eta_2'(t) + \eta_3'(t) + \eta_4'(t) + \eta_5'(t) + \eta_{\mathbf{P1}}'(t) \right) \right) + \\
& \left(M_{\mathbf{P1}} \left(\cos(\theta(t)) R(t) + \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left(L_0 + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \right. \right. \right. \\
& \quad \left. \left. \left. \eta_5(t) + \eta_{\mathbf{P1}}(t) \right) \right)^2 + i_{\mathbf{xP1}} \right) \zeta_{\mathbf{P1}}''(t) = -c_{10} \left(\zeta_{\mathbf{P1}}'(t) - \zeta_1'(t) \right)
\end{aligned}$$