

$$\begin{aligned}
& k_{10} (\zeta_1(t) - \zeta_2(t)) - k_{10} (\zeta_{P1}(t) - \zeta_1(t)) + \\
& 2 m_0 \left(\cos(\theta(t)) R(t) + \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left(\frac{9 L_0}{10} + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) \right) \right) \zeta_1'(t) \\
& \left(\cos(\theta(t)) R'(t) - \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left(\frac{9 L_0}{10} + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) \right) \alpha'(t) - \right. \\
& \quad \left. R(t) \sin(\theta(t)) \theta'(t) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left(\frac{9 L_0}{10} + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) \right) \right. \\
& \quad \left. (\theta'(t) + \psi'(t)) + \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_1'(t) + \eta_2'(t) + \eta_3'(t) + \eta_4'(t) + \eta_5'(t)) \right) + \\
& \left(m_0 \left(\cos(\theta(t)) R(t) + \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left(\frac{9 L_0}{10} + \eta_1(t) + \eta_2(t) + \eta_3(t) + \eta_4(t) + \eta_5(t) \right) \right) \right)^2 + \\
& i_{x_{m1}} \left. \right) \zeta_1''(t) = c_{10} (\zeta_{P1}'(t) - \zeta_1'(t)) - c_{10} (\zeta_1'(t) - \zeta_2'(t))
\end{aligned}$$