

$$\begin{aligned}
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) M_{P2} \left(\cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right) \zeta_{P2}'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) M_{P2} \\
& \left(\cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right) \chi_{P2}'(t)^2 - k_0 (\eta_2(t) - \eta_{P2}(t)) - \\
& \frac{1}{2} M_{P2} \left(2 \left(\cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \right) \right. \\
& \left(\cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \right. \\
& \left. R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left(-\cos(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \sin(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) + \\
& 2 \left(\sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \right) \\
& \left(\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) + \right. \\
& \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) + \frac{1}{2} M_{P2} \\
& \left(2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) \left(\cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right) \right. \\
& \left. \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& (\theta'(t) + \psi'(t)) \left(\cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \right. \\
& \left. R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left(-\cos(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \sin(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) \\
& \left(\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) + \right. \\
& \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& (\theta'(t) + \psi'(t)) \left(\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) + \right. \\
& \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left(\cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t)^2 - \right. \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t))^2 - 2 \sin(\theta(t)) R'(t) \theta'(t) + \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_2'(t) + \eta_{P2}'(t)) + \cos(\theta(t)) R''(t) + \\
& \left. \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha''(t) - R(t) \sin(\theta(t)) \theta''(t) + \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta''(t) + \psi''(t)) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2''(t) + \eta_{P2}''(t)) \Big) - \\
& 2 \sin(\alpha(t)) \Big(\sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t)^2 - 2 \cos(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \alpha'(t) - \\
& \cos(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha''(t) - \sin(\alpha(t)) (\eta_2''(t) + \eta_{P2}''(t)) \Big) - \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \Big(\cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t)^2 + \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t)^2 + \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t))^2 + 2 \cos(\theta(t)) R'(t) \theta'(t) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_2'(t) + \eta_{P2}'(t)) + \sin(\theta(t)) R''(t) + \\
& \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha''(t) + \cos(\theta(t)) R(t) \theta''(t) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta''(t) + \psi''(t)) - \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2''(t) + \eta_{P2}''(t)) \Big) \Big) + \\
& \Big(\mu M_{P2} \Big(2 (L_0 + \eta_2(t) + \eta_{P2}(t)) \sin^2(\alpha(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& (\cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t))) - \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t))) \Big) \Big) / \\
& \Big(2 \Big(\sin^2(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t))^2 + \\
& (\cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)))^2 + (R(t) \sin(\theta(t)) - \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)))^2 \Big)^{3/2} \Big) = -c_0 (\eta_2'(t) - \eta_{P2}'(t))
\end{aligned}$$