

$$\begin{aligned}
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) m_0 \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \right) \zeta_2'(t)^2 + \cos(\alpha(t)) \\
& \cos(\theta(t) + \psi(t)) M_{P2} \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right) \zeta_{P2}'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) m_0 \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \right) \chi_2'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) M_{P2} \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right) \\
& \chi_{P2}'(t)^2 + k_0 \eta_2(t) + k_0 (\eta_2(t) - \eta_{P2}(t)) - \\
& \frac{1}{2} m_0 \left( 2 \left( \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \right) \right. \\
& \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \right. \\
& \left. \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \eta_2'(t) \right) - \right. \\
& \left. 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) - \sin(\alpha(t)) \eta_2'(t) \right) + \right. \\
& \left. 2 \left( \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \right) \right. \\
& \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \right. \\
& \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \eta_2'(t) \right) \right) \Bigg) - \\
& \frac{1}{2} M_{P2} \left( 2 \left( \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \right) \right. \\
& \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \right. \\
& \left. R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) - \right. \\
& \left. 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \sin(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) + \right. \\
& \left. 2 \left( \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \right) \right. \\
& \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) + \right. \\
& \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \right) \right) \Bigg) + \\
& \frac{1}{2} m_0 \left( 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) - \right. \right.
\end{aligned}$$

$$\begin{aligned}
& R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \eta_2'(t) \Bigg) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \\
& \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \eta_2'(t) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) - \sin(\alpha(t)) \eta_2'(t) \right) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) + \right. \\
& \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \eta_2'(t) \right) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \\
& \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \right. \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \eta_2'(t) \right) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t)^2 - 2 \sin(\alpha(t)) \right. \\
& \left. \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) \alpha'(t) + 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \eta_2'(t) \right. \\
& \left. \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t))^2 - \right. \\
& \left. 2 \sin(\theta(t)) R'(t) \theta'(t) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \eta_2'(t) + \right. \\
& \left. \cos(\theta(t)) R''(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha''(t) - R(t) \sin(\theta(t)) \theta''(t) + \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta''(t) + \psi''(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \eta_2''(t) \right) - \\
& 2 \sin(\alpha(t)) \left( \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t)^2 - 2 \cos(\alpha(t)) \eta_2'(t) \alpha'(t) - \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha''(t) - \sin(\alpha(t)) \eta_2''(t) \Bigg) - \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha'(t)^2 + 2 \cos(\theta(t) + \psi(t)) \right. \\
& \quad \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t)) \alpha'(t) + 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \eta_2'(t) \alpha'(t) - \\
& \quad R(t) \sin(\theta(t)) \theta'(t)^2 + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta'(t) + \psi'(t))^2 + \\
& \quad 2 \cos(\theta(t)) R'(t) \theta'(t) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \eta_2'(t) + \sin(\theta(t)) R''(t) + \\
& \quad \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \alpha''(t) + \cos(\theta(t)) R(t) \theta''(t) - \cos(\alpha(t)) \\
& \quad \left. \left. \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) (\theta''(t) + \psi''(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \eta_2''(t) \right) \right) \Bigg) + \\
& \frac{1}{2} M_{P2} \Big( 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) (\cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \\
& \quad (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \Big) + \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \\
& \quad (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \Big) - \\
& 2 \cos(\alpha(t)) \alpha'(t) (-\cos(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) - \sin(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \Big) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) \\
& \quad (\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) + \\
& \quad \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \\
& \quad \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \Big) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& \quad (\theta'(t) + \psi'(t)) (\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t) + \\
& \quad \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \\
& \quad \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \Big) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \Big( \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t)^2 - \\
& \quad 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& \quad 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \\
& \quad \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t))^2 - 2 \sin(\theta(t)) R'(t) \theta'(t) + \\
& \quad 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_2'(t) + \eta_{P2}'(t)) + \cos(\theta(t)) R''(t) + \\
& \quad \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha''(t) - R(t) \sin(\theta(t)) \theta''(t) +
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta''(t) + \psi''(t)) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_2''(t) + \eta_{P2}''(t)) \Big) - \\
& 2 \sin(\alpha(t)) \Big( \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t)^2 - 2 \cos(\alpha(t)) (\eta_2'(t) + \eta_{P2}'(t)) \alpha'(t) - \\
& \cos(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha''(t) - \sin(\alpha(t)) (\eta_2''(t) + \eta_{P2}''(t)) \Big) - \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \Big( \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha'(t)^2 + \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2'(t) + \eta_{P2}'(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t)^2 + \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t))^2 + 2 \cos(\theta(t)) R'(t) \theta'(t) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_2'(t) + \eta_{P2}'(t)) + \sin(\theta(t)) R''(t) + \\
& \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \alpha''(t) + \cos(\theta(t)) R(t) \theta''(t) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) (\theta''(t) + \psi''(t)) - \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_2''(t) + \eta_{P2}''(t)) \Big) \Big) + \\
& \left( \mu m_0 \left( 2 \left( \frac{L_0}{2} + \eta_2(t) \right) \sin^2(\alpha(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \right. \\
& \quad \left. \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \right) \right) - \\
& \quad 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \right) \Big) \Big) / \\
& \left( 2 \left( \sin^2(\alpha(t)) \left( \frac{L_0}{2} + \eta_2(t) \right)^2 + \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \right)^2 + \right. \right. \\
& \quad \left. \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_2(t) \right) \right)^2 \right)^{3/2} \Big) + \\
& \left( \mu M_{P2} \left( 2 (L_0 + \eta_2(t) + \eta_{P2}(t)) \sin^2(\alpha(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \right. \\
& \quad \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right) - \\
& \quad 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t))) \Big) \Big) / \\
& \left( 2 \left( \sin^2(\alpha(t)) (L_0 + \eta_2(t) + \eta_{P2}(t))^2 + \right. \right. \\
& \quad \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right)^2 + \\
& \quad \left. \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_2(t) + \eta_{P2}(t)) \right)^2 \right)^{3/2} \Big) = \\
& c_0 (\eta_{P2}'(t) - \eta_2'(t)) - c_0 \eta_2'(t)
\end{aligned}$$