

$$\begin{aligned}
& -k_0 (\eta_7(t) - \eta_8(t)) + k_0 (\eta_8(t) - \eta_9(t)) - \\
& \frac{1}{2} m_0 \left( 2 (\cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t))) \right. \\
& \quad \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) - \right. \\
& \quad \left. R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) - \right. \\
& \quad \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) \right) - 2 \cos(\alpha(t)) \alpha'(t) \\
& \quad \left( -\cos(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) - \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) + \\
& 2 (\sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t))) \\
& \quad \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) + \right. \\
& \quad \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) - \right. \\
& \quad \left. \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) \right) \Bigg) - \\
& \frac{1}{2} m_0 \left( 2 (\cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t))) \right. \\
& \quad \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) - \right. \\
& \quad \left. R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \right. \\
& \quad \left. (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) - \right. \\
& \quad \left. \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \right) + \\
& 2 (\sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t))) \\
& \quad \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) + \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \\
& \left( \theta'(t) + \psi'(t) \right) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) \right) \Bigg) - \\
& \frac{1}{2} m_0 \left( 2 \left( \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \theta'(t) + \psi'(t) \right) \right) \right. \\
& \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \\
& \left. \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \right. \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) - \right. \\
& \left. \sin(\alpha(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) + \\
& 2 \left( \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \theta'(t) + \psi'(t) \right) \right) \\
& \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \left. \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \right. \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) \Bigg) - \\
& \frac{1}{2} M_{P2} \left( 2 \left( \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \theta'(t) + \psi'(t) \right) \right) \right. \\
& \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \right. \\
& \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \\
& \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t) \right) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \alpha'(t) - \right.
\end{aligned}$$

$$\begin{aligned}
& \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) + \\
& 2 (\sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t))) \\
& (\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \\
& \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t))) + \\
& \frac{1}{2} m_0 \left( 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \right. \\
& \left. \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \right. \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \left. (\theta'(t) + \psi'(t)) \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) - \right. \right. \\
& \left. \left. R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) - \right. \right. \\
& \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) - 2 \cos(\alpha(t)) \alpha'(t) \right. \\
& \left. \left( -\cos(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) - \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) + \right. \\
& \left. 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) \right. \\
& \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) + \right. \\
& \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) - \right. \\
& \left. \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \right) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \\
& \left. (\theta'(t) + \psi'(t)) \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t) + \right. \right. \\
& \left. \left. \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) - \right. \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) \right) \Bigg) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t)^2 - \right. \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t))^2 - \\
& 2 \sin(\theta(t)) R'(t) \theta'(t) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) + \\
& \cos(\theta(t)) R''(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha''(t) - \\
& R(t) \sin(\theta(t)) \theta''(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \\
& \left. (\theta''(t) + \psi''(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t)) \right) \Bigg) - 2 \sin(\alpha(t)) \\
& \left( \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t)^2 - 2 \cos(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \alpha'(t) - \right. \\
& \cos(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha''(t) - \sin(\alpha(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t)) \Bigg) - \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha'(t)^2 + \right. \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t)^2 + \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) (\theta'(t) + \psi'(t))^2 + \\
& 2 \cos(\theta(t)) R'(t) \theta'(t) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t)) + \\
& \sin(\theta(t)) R''(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \alpha''(t) + \\
& \left. \cos(\theta(t)) R(t) \theta''(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \right)
\end{aligned}$$

$$\begin{aligned}
& \left( \theta''(t) + \psi''(t) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t)) \right) \Bigg) + \\
& \frac{1}{2} m_0 \left( 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \right. \\
& \quad \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \\
& \quad \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t)) - \\
& \quad \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \right) \right) + \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \left( \cos(\theta(t)) R'(t) + \right. \\
& \quad \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \\
& \quad \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t)) - \\
& \quad \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \right) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) - \right. \\
& \quad \left. \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \right) + 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) \\
& \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) + \right. \\
& \quad \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \\
& \quad \left. (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \right) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \quad \left. \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t)) - \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \Big) - 2 \cos(\alpha(t)) \\
& \cos(\theta(t) + \psi(t)) \left( \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t)^2 - \right. \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t))^2 - 2 \sin(\theta(t)) \\
& R'(t) \theta'(t) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) + \\
& \cos(\theta(t)) R''(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha''(t) - \\
& R(t) \sin(\theta(t)) \theta''(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \\
& (\theta''(t) + \psi''(t)) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t)) \Big) - \\
& 2 \sin(\alpha(t)) \left( \sin(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t)^2 - \right. \\
& 2 \cos(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \alpha'(t) - \\
& \cos(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha''(t) - \\
& \sin(\alpha(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t)) \Big) - 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \left( \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha'(t)^2 + \right. \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t)) \alpha'(t) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t)^2 + \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) (\theta'(t) + \psi'(t))^2 + 2 \cos(\theta(t)) \\
& R'(t) \theta'(t) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t)) +
\end{aligned}$$

$$\begin{aligned}
& \sin(\theta(t)) R''(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \alpha''(t) + \\
& \cos(\theta(t)) R(t) \theta''(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \\
& \left( \theta''(t) + \psi''(t) \right) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) \right) \Bigg) + \\
& \frac{1}{2} m_0 \left( 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \right. \\
& \quad \left. \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \right. \\
& \quad \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \right. \\
& \quad \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) + \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \theta'(t) + \psi'(t) \right) \left( \cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \\
& \quad \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t) + \\
& \quad \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \right. \\
& \quad \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) - \\
& 2 \cos(\alpha(t)) \alpha'(t) \left( -\cos(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) - \right. \\
& \quad \left. \sin(\alpha(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \quad \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \\
& \quad \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \Bigg) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \theta'(t) + \psi'(t) \right) \left( \sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \quad \left. \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \right. \\
& \quad \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) - \\
& \quad \left. \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \right) \right) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \\
& \quad \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t)^2 - 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right) \alpha'(t) + 2 \cos(\theta(t) + \psi(t)) \\
& \quad \sin(\alpha(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \\
& \quad \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta'(t) + \psi'(t) \right)^2 - \\
& \quad 2 \sin(\theta(t)) R'(t) \theta'(t) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \theta'(t) + \psi'(t) \right) \\
& \quad \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) + \cos(\theta(t)) R''(t) + \cos(\theta(t) + \psi(t)) \\
& \quad \sin(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha''(t) - R(t) \sin(\theta(t)) \theta''(t) + \\
& \quad \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \left( \theta''(t) + \psi''(t) \right) - \\
& \quad \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) + \eta_{10}''(t) \right) \right) \Bigg) - \\
& 2 \sin(\alpha(t)) \left( \sin(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t)^2 - \right. \\
& \quad 2 \cos(\alpha(t)) \left( \eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) \right) \alpha'(t) - \\
& \quad \left. \cos(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha''(t) - \right.
\end{aligned}$$



$$\begin{aligned}
& \left. \sin(\alpha(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) + \eta_{10}''(t)) \right) - 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \left( \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha'(t)^2 + \right. \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) (\theta'(t) + \psi'(t)) \\
& \alpha'(t) + 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t)) \alpha'(t) - R(t) \\
& \sin(\theta(t)) \theta'(t)^2 + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \\
& (\theta'(t) + \psi'(t))^2 + 2 \cos(\theta(t)) R'(t) \theta'(t) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \\
& (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t)) + \sin(\theta(t)) R''(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \alpha''(t) + \cos(\theta(t)) R(t) \theta''(t) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) (\theta''(t) + \psi''(t)) - \\
& \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) + \eta_{10}''(t)) \right) \Bigg) + \\
& \frac{1}{2} M_{P2} \left( 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \alpha'(t) (\cos(\theta(t)) R'(t) + \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \right. \\
& (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t) - \\
& R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) \Bigg) + \\
& 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\cos(\theta(t)) R'(t) + \\
& \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t) - \\
& R(t) \sin(\theta(t)) \theta'(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) \Bigg) - \\
& 2 \cos(\alpha(t)) \alpha'(t) (-\cos(\alpha(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t) - \\
& \sin(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) \Bigg) + \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \alpha'(t) (\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t) + \\
& \cos(\theta(t)) R(t) \theta'(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) (\theta'(t) + \psi'(t)) -
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) - \\
& 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) (\sin(\theta(t)) R'(t) + \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t) + \cos(\theta(t)) R(t) \theta'(t) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \\
& \quad (\theta'(t) + \psi'(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& (\cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t)^2 - \\
& 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \\
& \quad (\theta'(t) + \psi'(t)) \alpha'(t) + 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) \\
& \quad (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) \alpha'(t) - \cos(\theta(t)) R(t) \theta'(t)^2 + \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \\
& \quad (\theta'(t) + \psi'(t))^2 - 2 \sin(\theta(t)) R'(t) \theta'(t) + 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \\
& \quad (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) + \cos(\theta(t)) R''(t) + \\
& \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha''(t) - \\
& R(t) \sin(\theta(t)) \theta''(t) + \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) (\theta''(t) + \psi''(t)) - \\
& \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) + \eta_{10}''(t) + \eta_{P2}''(t)) - \\
& 2 \sin(\alpha(t)) (\sin(\alpha(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t)^2 - \\
& 2 \cos(\alpha(t)) (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) \alpha'(t) - \\
& \cos(\alpha(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha''(t) - \sin(\alpha(t)) \\
& \quad (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) + \eta_{10}''(t) + \eta_{P2}''(t)) - 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& (\cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha'(t)^2 + \\
& 2 \cos(\theta(t) + \psi(t)) \sin(\alpha(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \\
& \quad (\theta'(t) + \psi'(t)) \alpha'(t) + 2 \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) \\
& \quad (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) \alpha'(t) - R(t) \sin(\theta(t)) \theta'(t)^2 + \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \\
& \quad (\theta'(t) + \psi'(t))^2 + 2 \cos(\theta(t)) R'(t) \theta'(t) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) (\theta'(t) + \psi'(t)) \\
& \quad (\eta_6'(t) + \eta_7'(t) + \eta_8'(t) + \eta_9'(t) + \eta_{10}'(t) + \eta_{P2}'(t)) + \sin(\theta(t)) R''(t) + \\
& \sin(\alpha(t)) \sin(\theta(t) + \psi(t)) (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) \alpha''(t) + \\
& \cos(\theta(t)) R(t) \theta''(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \\
& \quad (L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t)) (\theta''(t) + \psi''(t)) - \\
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) (\eta_6''(t) + \eta_7''(t) + \eta_8''(t) + \eta_9''(t) + \eta_{10}''(t) + \eta_{P2}''(t)) +
\end{aligned}$$

$$\begin{aligned}
& \left( \mu m_0 \left( 2 \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \sin^2(\alpha(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \right. \\
& \quad \left. \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \right) - 2 \cos(\alpha(t)) \right. \\
& \quad \left. \left. \sin(\theta(t) + \psi(t)) \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \right) \right) \right) / \\
& \left( 2 \left( \sin^2(\alpha(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right)^2 + \right. \right. \\
& \quad \left. \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \right)^2 + \right. \\
& \quad \left. \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{L_0}{2} + \eta_6(t) + \eta_7(t) + \eta_8(t) \right) \right)^2 \right)^{3/2} \Bigg) + \\
& \left( \mu m_0 \left( 2 \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \sin^2(\alpha(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \right. \\
& \quad \left. \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \right) - 2 \right. \\
& \quad \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \quad \left. \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \right) \right) \Bigg) / \\
& \left( 2 \left( \sin^2(\alpha(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right)^2 + \right. \right. \\
& \quad \left. \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \right)^2 + \right. \\
& \quad \left. \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{7 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) \right) \right)^2 \right)^{3/2} \Bigg) + \\
& \left( \mu m_0 \left( 2 \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \sin^2(\alpha(t)) - 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \right. \right. \\
& \quad \left. \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \right) \right) - \\
& \quad \left. 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( R(t) \sin(\theta(t)) - \right. \right.
\end{aligned}$$

$$\begin{aligned}
& \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \Bigg) \Bigg) \Bigg) \Bigg) / \\
& \left( 2 \left( \sin^2(\alpha(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right)^2 + \left( \cos(\theta(t)) R(t) - \cos(\alpha(t)) \cos(\theta(t) + \right. \right. \right. \\
& \quad \left. \left. \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \right)^2 + \left( R(t) \sin(\theta(t)) - \right. \right. \\
& \quad \left. \left. \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( \frac{9 L_0}{10} + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) \right) \right)^2 \right)^{3/2} \Bigg) + \\
& \left( \mu M_{P2} \left( 2 \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \sin^2(\alpha(t)) - \right. \right. \\
& \quad 2 \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( \cos(\theta(t)) R(t) - \right. \\
& \quad \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \right) - \\
& \quad 2 \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \right. \\
& \quad \left. \left. \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \right) \right) \Bigg) \Bigg) / \\
& \left( 2 \left( \sin^2(\alpha(t)) \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right)^2 + \left( \cos(\theta(t)) R(t) - \right. \right. \right. \\
& \quad \left. \left. \cos(\alpha(t)) \cos(\theta(t) + \psi(t)) \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \right)^2 + \right. \\
& \quad \left. \left( R(t) \sin(\theta(t)) - \cos(\alpha(t)) \sin(\theta(t) + \psi(t)) \left( L_0 + \eta_6(t) + \eta_7(t) + \eta_8(t) + \right. \right. \right. \\
& \quad \left. \left. \left. \eta_9(t) + \eta_{10}(t) + \eta_{P2}(t) \right) \right)^2 \right)^{3/2} \Bigg) = c_0(\dot{\eta}_7 - \dot{\eta}_8) - c_0(\dot{\eta}_8 - \dot{\eta}_9)
\end{aligned}$$